An alpha-numeric character generator for a computer display.

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AN ALPHA-NUMERIC CHARACTER GENERATOR
FOR A COMPUTER DISPLAY

by
K.G. SREENIVASAN

A Thesis
Submitted to the Faculty of Graduate Studies through the
Department of Electrical Engineering in Partial Fulfillment
of the Requirements for the Degree of
Master of Applied Science at the
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1969
ABSTRACT

This thesis describes the logical design and implementation of an economical cathode ray tube alpha-numeric display unit for a Digital Equipment Corporation PDP-8/S digital computer.

The above device is capable of displaying a part of the stored data in the computer memory on a cathode ray tube screen at the rate of approximately 200 characters per second with good legibility and flicker-free. This rate could be increased depending upon the writing speed of the oscilloscope used.

Each displayed character is formed by a series of dots selected from a 5 x 7 matrix of dots. These dots are in turn generated on the cathode ray tube screen by a set of unblanking pulses, fed to the Z-axis of the cathode ray tube in synchronism with the blanked beam movement.

A storage oscilloscope is used to overcome the flicker problem obviating the use of a delay line memory or a core memory. This greatly reduces the cost of the whole unit. Any conventional storage oscilloscope having a saw-tooth output can be used for the purpose.
A suitable time base circuit has been designed and constructed for providing flexibility in positioning the character on the screen and also control over the start, stop operation of the device.

The main advantage of this device lies in its simplicity in logical design. It also affords the flexibility for changing the shape of the character by a suitable addition and/or deletion of any of the pulses that go to make up the character.
ACKNOWLEDGEMENTS

The author wishes to express his appreciation to Dr. P.A.V. Thomas for suggesting this project and for his able guidance throughout its completion. Acknowledgement must also go to the National Research Council of Canada for the financial aid which made this project possible.
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CHAPTER I

INTRODUCTION

1.1. Need for a cathode ray display unit:

The increasing use of high speed digital computers has created a demand for high speed read out. This demand has stimulated the development of methods for generating alpha-numeric and symbolic information from coded digital inputs. There are various methods of visualising the digital information such as printing on paper, displaying on gas filled indicator tubes or displaying the data on cathode ray tube (c.r.t.) screen. The principal advantage of displaying computer generated information on a c.r.t. screen over other methods lies in its speed of operation. For instance the c.r.t. display units can display up to 2500 characters per second, the limitation being the type of memory buffer and c.r.t. used and also the operating speed of the computer, as compared to a teletype which can output only about 10 characters per second. The c.r.t. display units also offer the possibility of displaying simultaneously a large number of characters in a small area.

With the addition of light pen device, the c.r.t. display units offer the possibility of modifying the displayed data. Yet another feature of the c.r.t. unit is its
noise free operation and the addition of general graphics.

All the above said features make the c.r.t. display unit, an attractive output unit for the computer, thereby providing a key solution to the problem of efficient communication between the computer and its users.

1.2. Methods used for generating characters on a c.r.t.:

The primary requirement of any method used for character generation is that the generated characters are legible and distinct. There are various methods available for the purpose of generating alpha-numeric characters on a c.r.t. screen satisfying the above requirement. A few of them will be described here along with the method chosen for the display unit constructed for the project under description.

2.5

1.2.1. Scanning:

The characters are formed on the c.r.t. screen in much the same way as the character formation on a television screen. The character information stored in the generator, is sequentially sampled in a predetermined order to obtain intensity signals for modulating the display generator output. The appropriate area of the display must be scanned in synchronism with the character generator. A small raster is generated separately by the control pulse generator...
which synchronizes the raster scan with the scanning of the character store. Refer to fig.1(a) for a typical character display generated by the scanning method.

1.2.2. Stroke or Waveform:

Each character is formed by a set of 45 degree angled strokes in addition to the horizontal and vertical strokes. The characters are stored in the generator as X and Y deflection and intensity information. This information is simultaneously sampled to form three parametric analog waveforms. These are used by the display generator to draw out the character much as a pencil is used. Refer fig. 1(b). Even though this method provides very good legibility for the displayed characters, it calls for complex circuitry to produce the strokes of the proper type to draw out the characters.

1.2.3. Beam Shaping:

In this method the characters are formed by passing the c.r.t. writing beam through a stencil mask. The mask contains all the characters to be displayed. The desired character is selected for display by a proper choice of X and Y coordinates of beam deflection. As it can be seen this method requires a specifically built c.r.t. and it is not suitable for use with the conventional oscilloscope. Refer to fig. 1(c).
Fig. 1. Methods of character generation

(a) Scanning

(b) Waveform

(c) Beam Shaping

(d) Dot Pattern
1.2.4. Dot Pattern:

Characters are formed by a set of selected dots usually from a $5 \times 7$ matrix of dots. These dots are formed on the face of the c.r.t. screen either by selection of suitable $X$ and $Y$ coordinates for each dot using digital to analog converters and blanking the beam movement when it changes position or by a set of unblanking pulses generated in synchronism with the beam movement which is blanked.

In the present available display units using the dot pattern with unblanking pulses, the pulse train required for each character is obtained by a proper selection of rows and columns of a core matrix memory. This memory usually consists of 35 magnetic cores in a $5 \times 7$ array. Each core contains a set and reset winding. In addition, a read out winding is threaded through the matrix to simulate the character to be displayed. These read out wires will provide the unique pulse train required for each character when all the columns are set and the rows are reset sequentially. Fig. 1(d) gives a typical display generated for a character using the dot pattern method.

The number of dots or scanning lines contained in the individual characters of Fig. 1(a), (d) can be increased to improve the resolution. But such an increase will increase the cost and size of the unit and decrease the writing speed.
1.3. Proposed method:

After a careful review of the various methods described above it was decided to adopt the dot pattern of character generation using unblanking pulses with the blanked beam movement, as it offered good legibility and also simplicity in logical design.

To generate the unique pulse train for each character, the costly magnetic core technique was not used. Instead a relatively cheap clock and gating circuitry were used for generating the required pulse train. To display these dots on the c.r.t. screen at the proper positions, a small raster was generated on the face of the c.r.t. screen in synchronism with the pulse train generation.

1.4. Flicker problem:

Once the characters are generated, they have to be maintained in such a way that the display is flicker free. This problem is traditionally overcome by providing a buffer memory and whole display being repeated such that no perceptible flicker appears on the c.r.t. But another and less costlier way of avoiding the flicker problem is to use the storage oscilloscope for the display. In the project under description, a storage oscilloscope has been used to economise in the overall design although this does not provide the possibility for changing a character or erasing a portion of the displayed data.
CHAPTER II

PDP-8/S

2.1. General description:

PDP-8/S is a small general purpose computer with a processor and a random access core memory of 4096 words. This is a serial, one address, fixed word length of 12 bits (plus parity) computer and uses 2's complement arithmetic. Alpha-numeric characters are stored in 8 bit ASCII code format. Standard features include indirect addressing, facilities for instruction skipping and program interruption as functions of input/output device conditions.

2.2. Interfacing facilities:

Since the maximum utilization of a computer system depends largely upon the flexibility and number of peripheral devices that can be attached to it, the PDP-8/S has been designed to interface readily with a broad variety of external equipment.

High capacity and high speed Input/Output capabilities of the PDP-8/S allow it to operate a variety of peripheral devices in addition to the standard teletype, tape reader etc. It can also be interfaced with c.r.t. display units and digital plotters. Interfacing of these devices to the computer requires no modifications and can be
achieved in the field.

2.3. Programmed data transfers: 7,10

All the data transfers between the peripheral equipment and the PDP-8/S computer, which are controlled by programmed instructions in the computer are known as programmed data transfers. This mode of operation utilizes the basic Input Output Transfer instruction, which is divided into three parts. Bits 0, 1 and 2 contain an operation code of 6 to specify the Input Output Transfer (IOT) micro instruction. Bits 3 through 8 serve as a device selection code, which is transmitted to all peripheral equipment and which activates only the equipment designated by a specific code number contained within these bits. Bits 9, 10 and 11 control the output of the IOP generator within the processor and enable or disable the generation of IOP1, IOP2, and IOP4 pulses during each IOT instruction. Figures 2, 3 show the decoding of an IOT instruction and its timing.

A bussed system of Input/Output data transfers imposes the following requirement on the peripheral device.

1. A device selector which samples the select code generated by the IOT instruction and when selected to produce the IOT command pulses in accordance with the computer generated input output pulses.
Fig. 2. Typical IOT Instruction Decoding

Fig. 3. PDP-8/S Instruction Timing

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2. A buffer register to store the information before transmitting to or receiving from the accumulator of PDP-8/S.
3. A status flipflop to indicate the ready or busy status of the peripheral device.

The device selector within each peripheral equipment monitors the device selection lines and enables pulse amplifiers when its assigned select code has been detected within bits 3 through 8 of an IOT instruction. When enabled in this manner the pulse amplifiers produce positive or negative IOT pulses when triggered by the associated IOP pulses. The IOT pulses in turn perform data transfers to or from the computer and also control functions within the peripheral equipment.

In preparation for a normal data transfer, the computer programme normally checks the ready status of the receiving device (indicated by a flip flop) by an IOT pulse and the result is indicated to the input/output skip facility. The input/output skip allows branching of the program based upon the condition or the availability of peripheral equipment, effectively making programmed decisions to continue the current program or jump to another subroutine that services a peripheral device.

The data transfers are carried out via the accum-
ulator, using upto 12 bits. The program places the contents of the memory location to be transferred in the accumulator and this information is supplied at the bussed connection for the transfer operation. Fig. 4 shows the information flow within the computer which effects programmed data transfers with input/output equipment.

2.4. Timing and IOP generator:

When the Instruction Register (IR) decoder detects an operation code, it identifies an IOT instruction and initiates operation of the IOP generator. The logic diagram is shown in fig. 5. It consists of three similar channels, each channel having a gated delay, a gated pulse amplifier and an output pulse amplifier. Each pulse amplifier is provided with a 2 input 'AND' gate. The binary 1 status of the one of the least significant bits of the instruction in the memory buffer supplies the conditioning level of each of these gates. The other input of the 2 input 'AND' gates are connected to the output of a pulse amplifier through two delay circuits as shown in the fig. 5. Thus depending upon the presence of bits 9, 10, and 11, the IOP1, IOP2 and IOP4 pulses are produced when pulse input of the corresponding 'AND' gate is triggered. The instruction bit that enables or disables generation of each IOP pulse, the corresponding number of the IOT pulse produced in the

* Refer to Appendix IV for logic symbols and notation used

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Fig. 4. PDP-8/S Programmed Data-Transfer Interface
Fig. 5. IOP Generator Logic
device selector and event time for each pulse is

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CHAPTER III

CHARACTER GENERATOR AND CONTROL UNIT

Before describing the details of the character generator and its operation, it is appropriate to describe the technique used to generate the character, in full and the required raster generation.

3.1. Raster generation:

A small raster is required to generate the character display on the c.r.t. screen. The width of this raster is equal to the height of the character displayed and this consists of 5 equally spaced near vertical lines. This can be achieved by applying sawtooth voltage waveforms to both horizontal and vertical deflection plates of the c.r.t. simultaneously. The vertical deflection sawtooth voltage waveform should be made to increase for a duration required to produce 7 pulses (by the clock) and then be reset. Now if this vertical deflection waveform is triggered 5 times at equal intervals namely by pulses 1, 8, 15, 22, 29 we can generate the 5 vertical lines required for the formation of the characters. Refer to fig. 6(b). In the present project this sawtooth waveform was obtained from the oscilloscope.

* Refer to fig. 17.
Fig. 6. Technique of character generation

(a) Horizontal deflection voltage waveform

(b) Vertical deflection voltage waveform

(c) Pulse train required to form character 'A'

(d) Character display as seen on c.r.t. screen

\[ t_h = \text{time required to generate 7 pulses (character height)} \]

\[ t_s = \text{time required to generate 14 pulses (character spacing)} \]

\[ t_t = \text{time required to generate 35 pulses (character time)} \]
The horizontal deflection voltage waveform should be made to increase for a duration required to produce 48 pulses, so that it has enough deflection to generate the character and to provide the spacing for the next to be generated and then held at the value reached at the end of 48 pulses. Again when another character is to be generated this horizontal deflection voltage should be made to increase from its previous value. It should also have facilities for resetting to its initial value after generating a certain number of characters. Fig. 6(a) shows the shape of the required horizontal deflection waveform. The circuit required to generate this voltage waveform was designed and constructed and is described under the chapter "Implementation".

In addition to these deflection voltages, it is required to generate a unique pulse train for each character and should be fed to the Z axis of the c.r.t. in synchronism with the raster generation. If the lines generated by the above said horizontal and vertical deflections are blanked and the pulse train is used as unblanking pulses, then the required display will be formed on the c.r.t. screen. The method of pulse train generation is described in the following paragraphs under the present chapter.

A complete diagram is given in fig. 6 showing the shape of horizontal and vertical deflection waveforms.
used, the pulse train required to generate the character 'A' and the actual display formed on the c.r.t. screen.

3.2. Description of the character generator

The character generator and control unit consists of a device selector, a buffer register for temporary storage of information, a character decoder, a clock, a counter and counter decoder and the associated gating circuitry for the generation of pulse trains. A block diagram of the character generator and the control unit is shown in fig. 7. The details and working of each of the above mentioned components are described below.

3.2.1. Device selector:

The logical representation of the device selector is shown in fig. 8. This consists of a 6 input 'NAND' gate and three gated pulse amplifiers. These 6 inputs correspond to bits 3 through 8 of the memory buffer register (MB). Since both negative and positive levels of memory buffer register bits are available at the bussed connection, any code between 00 and 77 can be generated by the proper selection of bit levels. For the project under description a code 33 was selected and connections were made accordingly as shown in the fig. 8. Thus, this device will be enabled only when a 33 is present in the IOT instruction.
Fig. 7. Block Diagram of the Proposed Character Generator Unit
Fig. 8. Device Selector Logic
The level output of this 'NAND' gate is connected to the level inputs of the three 2 input 'AND' gates feeding the three pulse amplifiers. The trigger inputs of these gates are connected to the 3 outputs of the IOP pulse generator of the computer. Hence, the three pulse amplifiers produce the 3 IOT pulses when properly enabled by the device select code and triggered by the corresponding IOP pulses. Both negative and positive output pulses are available, which are used for control purposes.

3.2.2. Buffer register:

The logical representation of the buffer register is shown in fig. 9. This is a 6 bit flip-flop register capable of storing a 6 bit information. Even though standard ASCII code uses an 8 bit code for the alpha-numeric characters, it was found that a 6 bit register is adequate for our purposes so long as no special character is required to be stored. Appendix I gives the codes used for each character. Information is transferred in parallel mode to this register from the computer via the accumulator under the program control of the PDP-8/S, as described earlier under programmed data transfers. Since this register is capable of storing only one character at a time, any character is held only for a time, that is required to display that particular character. As the computer can transfer characters
Fig. 9. Buffer Register

- CLEAR PULSE
- TRANSFER PULSE

BIT 1

BIT 6

LEVEL OUTPUT
DAC Bit 6
DAC Bit 11
at a rate much faster than the time required to generate them on the screen, it must be kept waiting till the transferred character is generated before another character is sent into the buffer. This is achieved by a device ready flip flop as explained later under 'Operation'.

3.2.3. Counter:

The counter used for this project is a 6 bit straight binary counter, whose logic diagram is shown in fig. 10. For clarity purposes interconnections between the flip flops are omitted in the diagram. Since this is a 6 bit counter, it is capable of counting up to \(2^6 = 64\) numbers. The counter is made to reset automatically after counting up to 48 through a NAND gate and a pulse amplifier. The first 35 counts are utilized to number the 5 x 7 matrix of pulses and the rest for providing the spacing time between the characters.

3.2.4. Counter decoder:

A series of 35, 7-input NAND gates, one each for each of the 35 pulses required to generate the 5 x 7 matrix of pulses, make up the counter decoder. The logic diagram of the counter decoder is shown in fig. 11. The six of the seven inputs are connected to the level outputs of the counter flip flops as required, and the seventh input is connected to the delayed clock pulse. The clock pulse must be
Fig. 10. 6-Bit binary Counter
Fig. 11. Counter Decoder
delayed before reaching the counter decoder, because the clock pulses which are used to change the state of the counter cannot be used to sample the counter at the same time, as this might result in ambiguity of the pulse number decoded. The delay was achieved by means of a single shot multivibrator circuit.

Thus each NAND gate is made to decode one pulse. For example the inputs of the NAND gate which decodes pulse number 1 are connected to the binary '0' outputs of flip-flops 2, 3, 4, 5, 6 and binary '1' output of flip-flop 1 of the counter.

As it can be seen only one NAND gate is enabled at any one time depending upon the number present in the counter at that time. The outputs of these NAND gates go to provide the 35 pulses required for the character generation. They also provide the triggering pulses for the time-base circuits.

3.2.5. Gating circuitry for the generation of pulse train:

Each character requires a set of pulses depending upon the its shape of formation. For each character an OR gate is required whose inputs are equal to the number of pulses required to form that particular character. The inputs of these OR gates are fed from the outputs of the coun-
ter decoder as required for each character. The shape of a character can be changed by changing the input connections of these OR gates. The pulses required to form each character and the shapes proposed are shown in Appendix II. As an example an OR gate with the input pulses required to form the character "A" is shown in fig. 12.

3.2.6. Character decoder:

A series of 7-input NAND gates, one each for selecting each character, make up the character decoder. The 6 of the 7 inputs are fed from the level outputs of the character generator buffer register flipflops to decode the character present in the buffer, and the seventh input is connected from the OR gate which sends the pulse train required to form the particular character decoded.

Thus it can be seen that when a particular character is selected, the pulse train to form that character is outputted by the character decoder. The logic diagram and the selection lines required to generate the character 'A' is shown in the fig. 13. For example, to select the character 'A' the 6 inputs of one NAND gate are connected to the binary '0' outputs of buffer register flipflops 1, 2, 3, 4, 5 and to the binary '1' output of flipflop 6 and the seventh input is connected to character 'A' OR gate.

The outputs of all these decoder NAND gates are
Fig. 12. Pulse selection 'OR' gates
Fig. 13. Character Decoder

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OHed together and fed to the grid of the CRT. to provide the intensification or unblanking pulses.

3.3. Operation of the character generator:

The entire operation of the character generator is program controlled. An IOT4 pulse is generated by the instruction \(633^1\) to test whether the device is ready to receive data. This operation is performed by a 2-input NAND gate in the device connected as shown in Fig. 14. One input of this skip gate receives the status level, (flag flip flop status), the second input receives the IOT4 pulse, and the output drives the computer I/O skip bus to ground when the skip conditions are satisfied. When the I/O skip bus is driven to ground, the content of the program counter is incremented by 1 to advance the program count without executing the instruction at the current program count. Programmed testing in this manner allows the routine to jump out of sequence to a subroutine that services the device tested. If the device is not ready, the computer keeps on checking the status flip flop till it indicates ready signal. Refer to Appendix III for the instructions required to perform this.

When the device does become ready, an IOT2 pulse is generated to reset the horizontal time-base voltage if required. After this an IOT1 pulse is generated which clears the counter and the buffer register. This same IOT1
Fig. 14. Use of IOS to test the Status of External Device
pulse delayed in time is used to cause the data transfer from the accumulator to the buffer register and to start the clock. It also sets the device ready flip flop to binary '0' status, thereby effectively blocking the computer from transferring more data to the buffer register. The device is made ready by the forty-ninth pulse, thus ensuring that the character originally transferred has been displayed before indicating to the computer that the device is ready to receive another data. Recall that it requires a time duration necessary to produce 48 pulses for the generation of a character and to provide the spacing for the next character.

The flow chart and the computer program required to generate one character is given in Appendix III. Photographs of the oscilloscope display are shown in fig. 18.
CHAPTER IV

IMPLEMENTATION

The character generator unit was implemented using 8 the DEC 'R' series NAND logic modules, the logic levels being 0 and -3 volts. A few of the 'A' series and 'W' series modules were employed wherever required.

The c.r.t. used for the display was a Tektronix cathode ray oscilloscope with storage facilities. Since this particular oscilloscope did not have a sawtooth output terminal, the vertical time base signal had to be obtained from some other oscilloscope. The horizontal time-base circuit was designed and constructed as shown in fig. 15.

The horizontal time-base circuit is an essentially integrate and hold circuit constructed using a Burr-Brown operational amplifier as shown in fig. 15 and can be analysed as follows:

For deriving the transfer function the following assumptions can be made for an operational amplifier:
1. Gain is infinite.
2. Input impedance is infinite.
3. Output impedance is zero.
4. The output occurs without any time lag.
5. The output voltage will be zero, when the input is zero.
Fig. 15. Horizontal deflection time-base circuit
Since the gain is almost infinite, if negative feedback is employed the potentials at nodes 1 and 2 will be the same. Refer to the fig. 15. When a capacitor is used for the negative feed back the circuit acts like an integrator as can be shown mathematically.

By Kirchoff's current law at node 1 which is approximately at '0' volts

\[-\frac{V_1}{R} = C \frac{dE_0}{dt}\]

Hence

\[E_0 = \int \frac{V_1}{(CR)} dt\]

Since \(V_1\) is a D.C. Voltage in our case

\[E_0 = -\frac{V_1 t}{(CR)} + \text{initial condition}\]

As the output voltage (maximum) \(E_0\) is specified for the amplifier, any combinations of \(C\) and \(R\) can be used to select the integrating time \(t\). If after a time \(t_1\) less than \(t\), the supply is disconnected the capacitor will hold the voltage stored in it at that time, as it cannot discharge through the amplifier due to its high impedance. Thus it generates the waveform required as shown in fig. 6 (a).

Transistor switches numbered 2 and 3 are closed and the switch number 1 is opened to reset the time-base output to
'0' volts through the resistors R1 and R2, by an IOT2 pulse. For the integration mode the switches 3 and 1 are closed and the switch 2 is opened by the first clock pulse. For hold conditions, the switches 1, 2, 3 are all opened by the clock pulse number forty nine, thus achieving the synchronism between the pulse train and the beam movement.
CHAPTER V

CONCLUSIONS

Even though the character generator unit was specifically constructed for the PDP-8/S computer, the general principles used in the design and construction can be extended to any interfaceable computer.

An attempt was made to set certain 'OR' gates common for certain characters which have some common pulses to economise in the overall unit. But, since this created certain changes in the logical functions, additional gates were required to generate the desired functions. Thus it was found that the total cost did not reduce to an appreciable extent. Though a slight reduction in cost was evident, this idea was abandoned in favour of the described scheme, since the latter afforded more flexibility to change the shape of any character, if required.

Due to the experimental nature of the project undertaken, (to test the concept of the method of character generation), the gating circuitry was carried out for only 2 characters and the representation being carried out on one line. However all the alpha-numeric characters can be generated by providing the required character 'OR' gates.
Also more lines of display can be achieved by employing a digital to analog converter and an associated counter. The analog output steps should be fed to the vertical deflection plates along with the sawtooth voltage which was used for the raster generation. The number of analog step outputs should be equal to the number of lines desired.

This project could be further extended by adding an additional input like a teletype and made more flexible by incorporating a light-pen device.
### APPENDIX I

**THE OCTAL CODES USED FOR THE CHARACTER REPRESENTATION**

<table>
<thead>
<tr>
<th>Character</th>
<th>Code used</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>01</td>
</tr>
<tr>
<td>B</td>
<td>02</td>
</tr>
<tr>
<td>C</td>
<td>03</td>
</tr>
<tr>
<td>D</td>
<td>04</td>
</tr>
<tr>
<td>E</td>
<td>05</td>
</tr>
<tr>
<td>F</td>
<td>06</td>
</tr>
<tr>
<td>G</td>
<td>07</td>
</tr>
<tr>
<td>H</td>
<td>10</td>
</tr>
<tr>
<td>I</td>
<td>11</td>
</tr>
<tr>
<td>J</td>
<td>12</td>
</tr>
<tr>
<td>K</td>
<td>13</td>
</tr>
<tr>
<td>L</td>
<td>14</td>
</tr>
<tr>
<td>M</td>
<td>15</td>
</tr>
<tr>
<td>N</td>
<td>16</td>
</tr>
<tr>
<td>O</td>
<td>17</td>
</tr>
<tr>
<td>P</td>
<td>20</td>
</tr>
<tr>
<td>Q</td>
<td>21</td>
</tr>
<tr>
<td>R</td>
<td>22</td>
</tr>
<tr>
<td>S</td>
<td>23</td>
</tr>
<tr>
<td>T</td>
<td>24</td>
</tr>
<tr>
<td>U</td>
<td>25</td>
</tr>
<tr>
<td>V</td>
<td>26</td>
</tr>
<tr>
<td>W</td>
<td>27</td>
</tr>
<tr>
<td>X</td>
<td>30</td>
</tr>
<tr>
<td>Y</td>
<td>31</td>
</tr>
<tr>
<td>Z</td>
<td>32</td>
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<td>0</td>
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<td>1</td>
<td>61</td>
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<td>3</td>
<td>63</td>
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<tr>
<td>4</td>
<td>64</td>
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<tr>
<td>5</td>
<td>65</td>
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<tr>
<td>6</td>
<td>66</td>
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<tr>
<td>7</td>
<td>67</td>
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<td>8</td>
<td>70</td>
</tr>
<tr>
<td>9</td>
<td>71</td>
</tr>
</tbody>
</table>
APPENDIX II

Fig. 16 Proposed patterns for the characters
Fig. 17. Dot Matrix with reference Numbers
<table>
<thead>
<tr>
<th>Character</th>
<th>Pulse numbers</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>1, 2, 3, 4, 5, 8, 10, 13, 17, 21, 24, 27, 29, 30, 31, 32, 33.</td>
</tr>
<tr>
<td>B</td>
<td>1, 2, 3, 4, 5, 6, 7, 8, 11, 14, 15, 18, 21, 22, 28, 30, 31, 33, 34</td>
</tr>
<tr>
<td>C</td>
<td>2, 3, 4, 5, 6, 8, 11, 14, 15, 21, 22, 28, 30, 34</td>
</tr>
<tr>
<td>D</td>
<td>1, 2, 3, 4, 5, 6, 7, 8, 14, 15, 21, 22, 28, 30, 31, 32, 33, 34</td>
</tr>
<tr>
<td>E</td>
<td>1, 2, 3, 4, 5, 6, 7, 8, 11, 14, 15, 18, 21, 22, 28, 29</td>
</tr>
<tr>
<td>F</td>
<td>1, 2, 3, 4, 5, 6, 7, 11, 14, 18, 21, 28, 35</td>
</tr>
<tr>
<td>G</td>
<td>2, 3, 4, 5, 6, 8, 14, 15, 17, 21, 22, 24, 28, 30, 31, 34</td>
</tr>
<tr>
<td>H</td>
<td>1, 2, 3, 4, 5, 6, 7, 11, 18, 25, 29, 30, 31, 32, 33, 34, 35</td>
</tr>
<tr>
<td>I</td>
<td>15, 16, 17, 18, 19, 20, 21</td>
</tr>
<tr>
<td>J</td>
<td>1, 2, 8, 14, 15, 16, 17, 18, 19, 20, 21, 28</td>
</tr>
<tr>
<td>K</td>
<td>1, 2, 3, 4, 5, 6, 7, 11, 17, 19, 23, 27, 29, 35</td>
</tr>
<tr>
<td>L</td>
<td>1, 2, 3, 4, 5, 6, 7, 8, 15, 22, 29</td>
</tr>
<tr>
<td>M</td>
<td>1, 2, 3, 4, 5, 6, 7, 14, 17, 18, 19, 28, 29, 30, 31, 32, 33, 34, 35</td>
</tr>
<tr>
<td>N</td>
<td>1, 2, 3, 4, 5, 6, 7, 13, 19, 25, 29, 30, 31, 32, 33, 34, 35</td>
</tr>
</tbody>
</table>

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<table>
<thead>
<tr>
<th>Character</th>
<th>Pulse numbers</th>
</tr>
</thead>
<tbody>
<tr>
<td>O</td>
<td>2, 3, 4, 5, 6, 8, 14, 15, 21, 22, 28, 30, 31, 32, 33, 34</td>
</tr>
<tr>
<td>P</td>
<td>1, 2, 3, 4, 5, 6, 7, 11, 14, 18, 21, 25, 28, 33, 34</td>
</tr>
<tr>
<td>Q</td>
<td>2, 3, 4, 5, 6, 8, 14, 15, 17, 21, 23, 28, 29, 31, 32, 33, 34</td>
</tr>
<tr>
<td>R</td>
<td>1, 2, 3, 4, 5, 6, 7, 11, 14, 18, 21, 24, 25, 28, 29, 30, 33, 34</td>
</tr>
<tr>
<td>S</td>
<td>2, 5, 6, 8, 11, 14, 15, 18, 21, 22, 25, 28, 30, 31, 34</td>
</tr>
<tr>
<td>T</td>
<td>7, 14, 15, 16, 17, 18, 19, 20, 21, 28, 35</td>
</tr>
<tr>
<td>U</td>
<td>2, 3, 4, 5, 6, 7, 8, 15, 22, 30, 31, 32, 33, 34, 35</td>
</tr>
<tr>
<td>V</td>
<td>3, 4, 5, 6, 7, 9, 15, 23, 31, 32, 33, 34, 35</td>
</tr>
<tr>
<td>W</td>
<td>1, 2, 3, 4, 5, 6, 7, 8, 16, 17, 18, 19, 22, 29, 30, 31, 32, 33, 34, 35</td>
</tr>
<tr>
<td>X</td>
<td>1, 2, 6, 7, 10, 12, 18, 24, 26, 29, 30, 34, 35</td>
</tr>
<tr>
<td>Y</td>
<td>6, 7, 12, 15, 16, 17, 18, 26, 34, 35</td>
</tr>
<tr>
<td>Z</td>
<td>1, 2, 7, 8, 10, 14, 15, 18, 21, 22, 26, 28, 29, 34, 35</td>
</tr>
</tbody>
</table>

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<table>
<thead>
<tr>
<th>Character</th>
<th>Pulse numbers</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>2, 3, 4, 5, 6, 8, 12, 14, 15, 18, 21, 22, 24, 28, 30, 31, 32, 33, 34</td>
</tr>
<tr>
<td>1</td>
<td>8, 13, 15, 16, 17, 18, 19, 20, 21, 22</td>
</tr>
<tr>
<td>2</td>
<td>1, 6, 8, 9, 14, 15, 17, 21, 22, 25, 28, 29, 33, 34</td>
</tr>
<tr>
<td>3</td>
<td>2, 6, 8, 14, 15, 18, 21, 22, 25, 28, 30, 31, 33, 34</td>
</tr>
<tr>
<td>4</td>
<td>3, 10, 11, 17, 19, 24, 27, 29, 30, 31, 32, 33, 34, 35</td>
</tr>
<tr>
<td>5</td>
<td>2, 5, 6, 7, 8, 12, 14, 15, 19, 21, 22, 26, 28, 30, 31, 32, 35</td>
</tr>
<tr>
<td>6</td>
<td>2, 3, 4, 5, 6, 8, 11, 14, 15, 18, 21, 22, 25, 28, 30, 31, 34</td>
</tr>
<tr>
<td>7</td>
<td>1, 7, 9, 14, 17, 21, 25, 28, 33, 34, 35</td>
</tr>
<tr>
<td>8</td>
<td>2, 3, 5, 6, 8, 11, 14, 15, 18, 21, 22, 25, 28, 30, 31, 33, 34</td>
</tr>
<tr>
<td>9</td>
<td>2, 5, 6, 8, 11, 14, 15, 18, 21, 22, 25, 28, 30, 31, 32, 33, 34</td>
</tr>
</tbody>
</table>
APPENDIX III

Flow chart for character generation

Start

Is Device ready

Yes

Reset the beam

Bring character to accumulator

Transfer character for generation

Is character generation complete

Yes

Halt

No

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*200
CLA CLL
6334 /CHECK IF DEVICE IS READY
JMP.-1 /IF NOT READY, CHECK AGAIN
6332 /IF READY, RESET THE BEAM
TAD A /BRING CHARACTER 'A' TO ACC
6331 /TRANSFER CHARACTER AND START
CHARACTER GENERATION ON CRT
6334 /CHECK IF CHARACTER GENERATION
IS COMPLETE
JMP.-1 /IF NOT COMPLETE CHECK AGAIN
HLT
A,301
C,303
$
Fig. 18. Oscilloscope display (Photographs).

(a) Single character (enlarged) with blanked raster

(b) A line representation (actual size)
APPENDIX IV

LOGIC NOTATION

In the detailed analysis given in this thesis of the operational sequences of character generator and PDP-8/S it is assumed that the reader is familiar with the fundamental concepts of logic and its notations. Many conventions exist, however the particular set chosen for this write-up is as follows:

<table>
<thead>
<tr>
<th>FUNCTION</th>
<th>SYMBOL</th>
<th>DESCRIPTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>AND</td>
<td>![AND symbol]</td>
<td>C = A . B</td>
</tr>
<tr>
<td>NAND</td>
<td>![NAND symbol]</td>
<td>C = \overline{A . B}</td>
</tr>
<tr>
<td>OR</td>
<td>![OR symbol]</td>
<td>C = A + B</td>
</tr>
<tr>
<td>NOT</td>
<td>![NOT symbol]</td>
<td>B = \overline{A}</td>
</tr>
<tr>
<td>DELAY</td>
<td>![DELAY symbol]</td>
<td>B = Delayed A</td>
</tr>
<tr>
<td>FLIP-FLOP</td>
<td>![FLIP-FLOP symbol]</td>
<td>B = Delayed A</td>
</tr>
</tbody>
</table>

(See below)

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The ON or SET output of the flip-flop is represented by 'A' and the OFF or RESET output is represented by 'A\text{'}\ '. When the flip-flop is set, A = 1 and \(\bar{A} = 0\) and when the flip-flop is reset, A = 0 and \(\bar{A} = 1\).

A flip-flop can be set either through Direct set input or by satisfying the AND gate fed by the set level input and AC set. Similar choices exist for resetting the flip-flop also.

The following rules govern the use of flip-flops.

1. The AC set and the AC reset inputs respond only to a logic level CHANGE from a '0' to a '1' state.
2. The Set level input (Reset level) be '1' prior to the activation of the AC set (AC reset) input if it is desired to operate the flip-flop. This lead time is equivalent to the memory time of the AND gate fed by these inputs.

The ONE SHOT generates a pulse output of fixed duration when triggered by the AC set input. The 'X' on its 0 input indicates this characteristic.
REFERENCES


VITA AUCTORIS

1941 Born on September 25, in Bommiidi, Madras, India.

1957 Completed Secondary School Education at Municipal High School, Gobichettipalayam, Madras, India.

1965 Graduated from Osmania University, Hyderabad, India, with the degree of B.E.(Hons) in Electrical Engineering.

1969 Candidate for the degree of M.A.Sc. in Electrical Engineering at the University of Windsor.